

FIG. 2

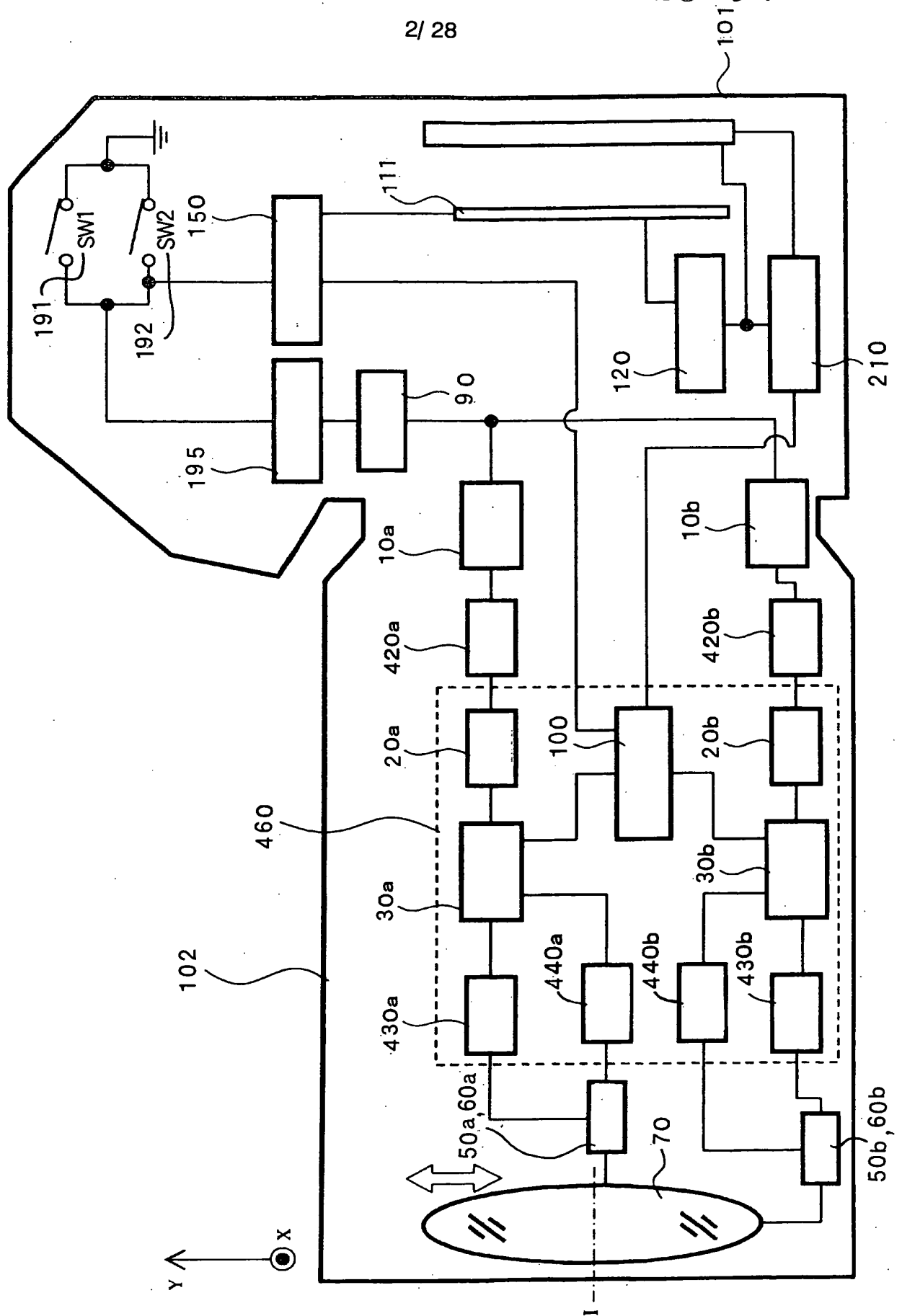


FIG. 3

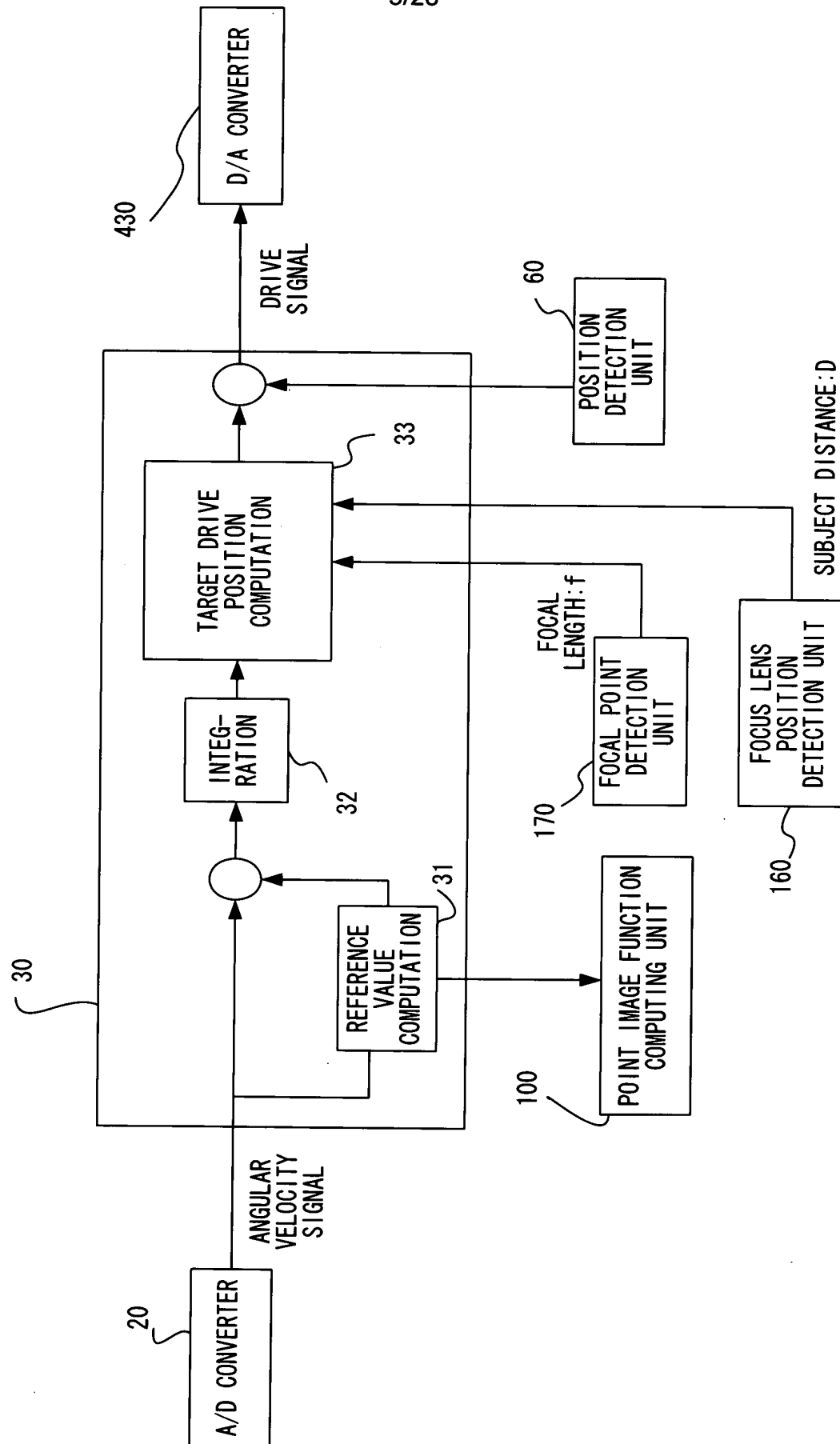


FIG.4

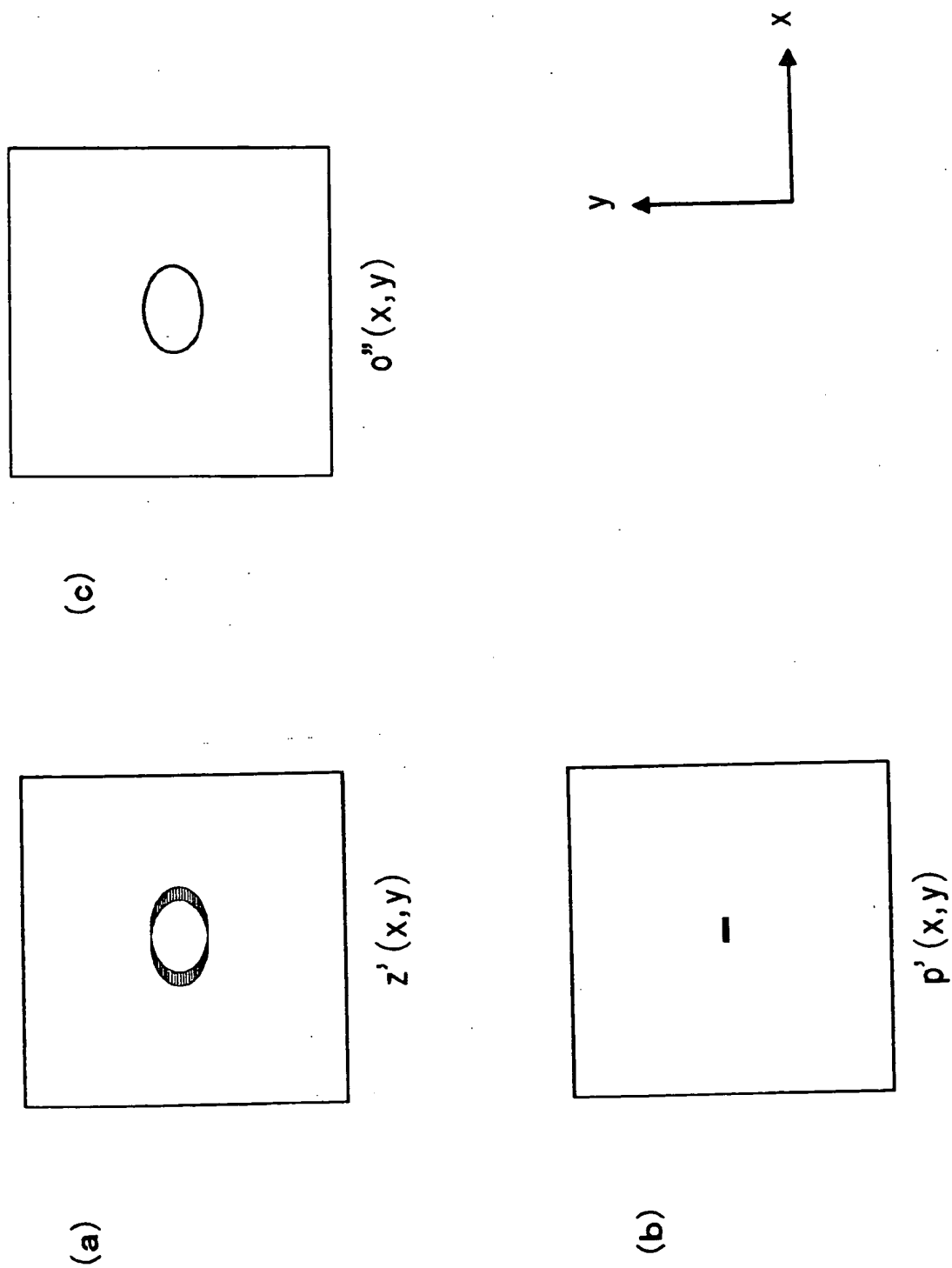
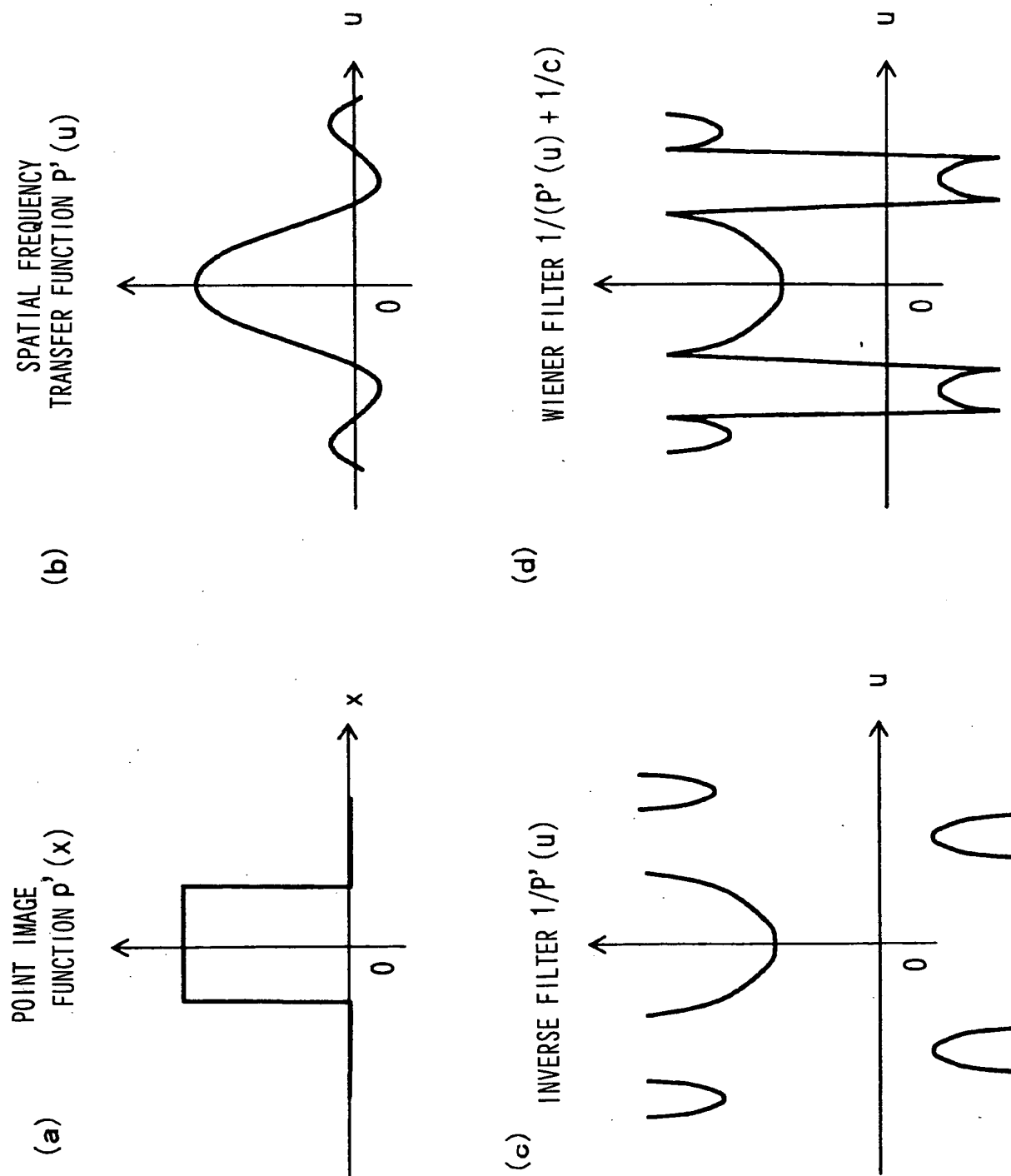
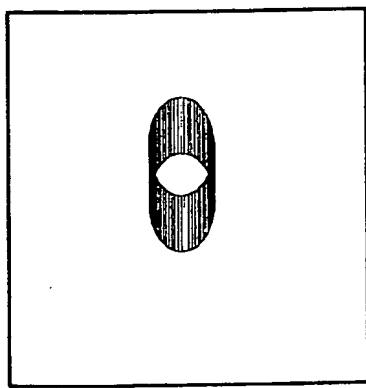


FIG.5

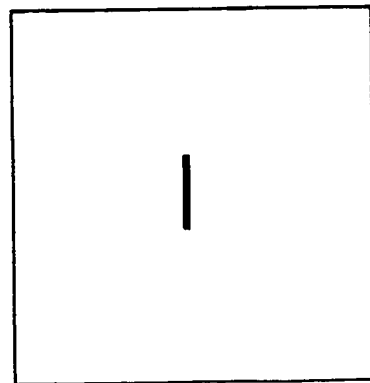


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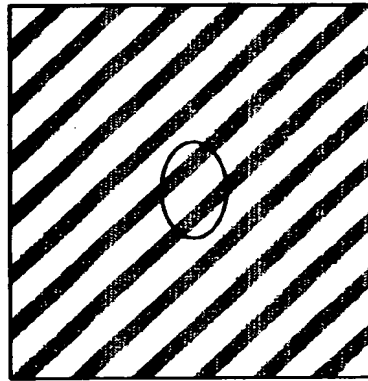
FIG.6



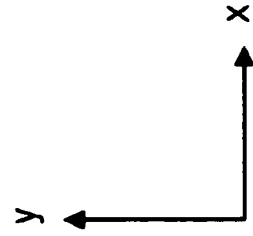
(a)

 $z(x,y)$ 

(b)

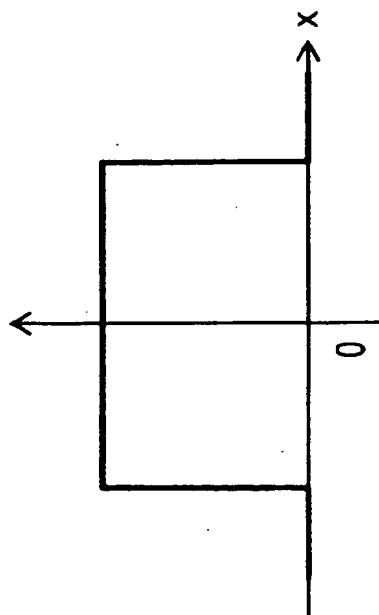
 $p(x,y)$ 

(c)

 $o'(x,y)$ 

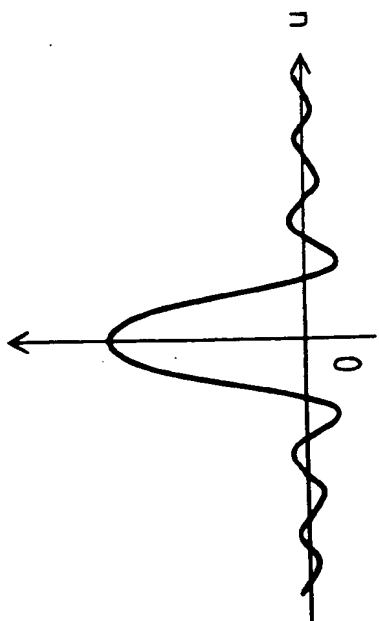
POINT IMAGE  
FUNCTION  $p(x)$

(a)

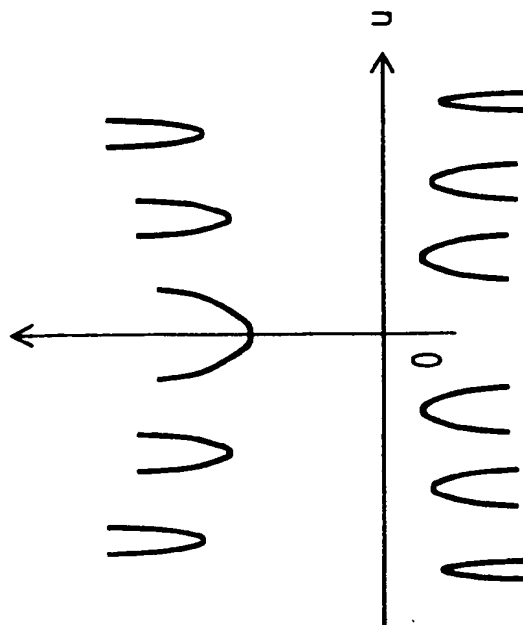


(b)

SPATIAL FREQUENCY  
TRANSFER FUNCTION  $P(u)$

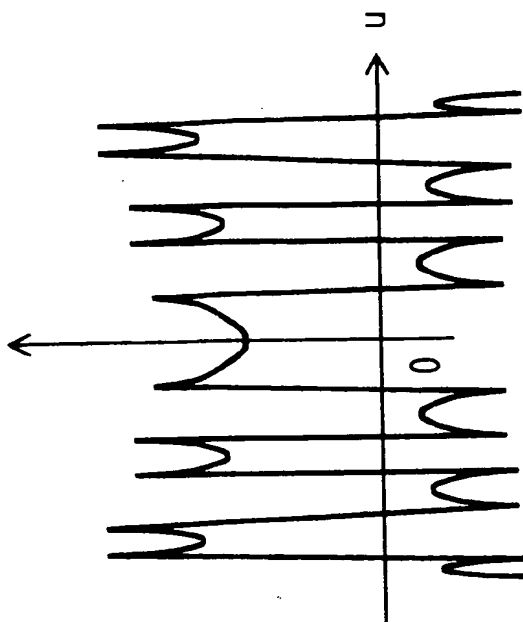


(c) INVERSE FILTER  $1/P(u)$



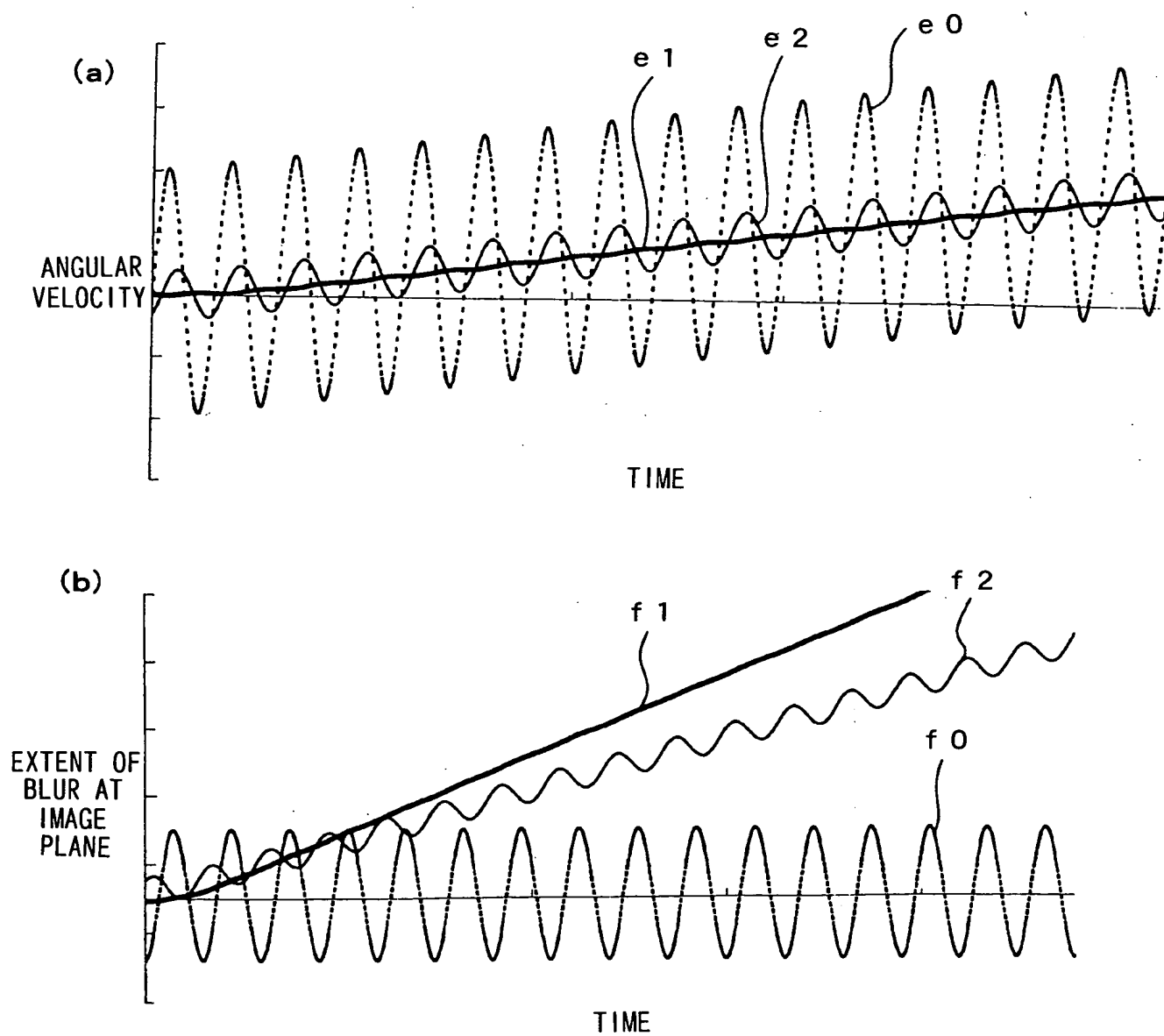
(d)

WIENER FILTER  $1/(P(u) + 1/c)$



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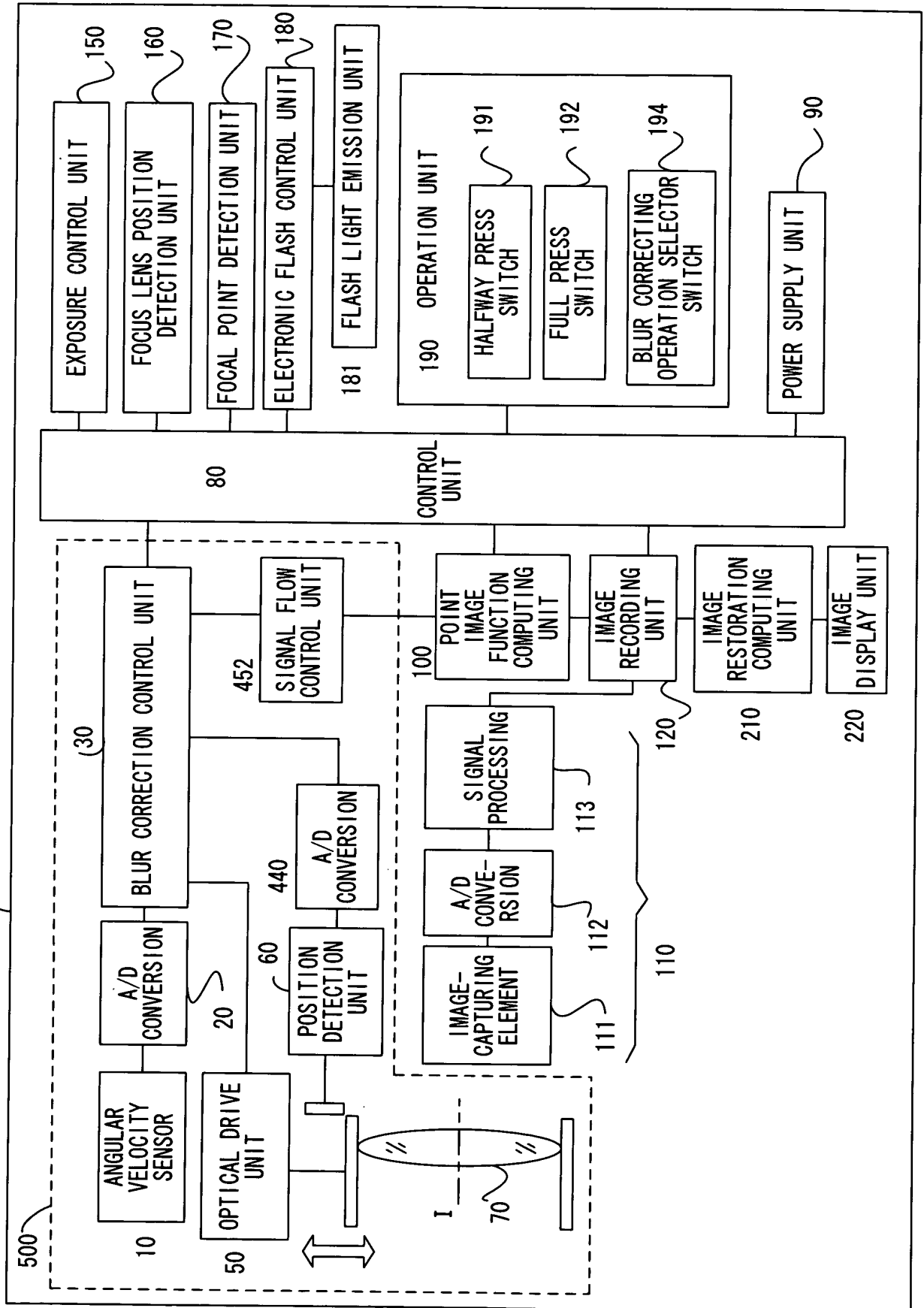
FIG.8





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FIG. 9





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FIG. 11

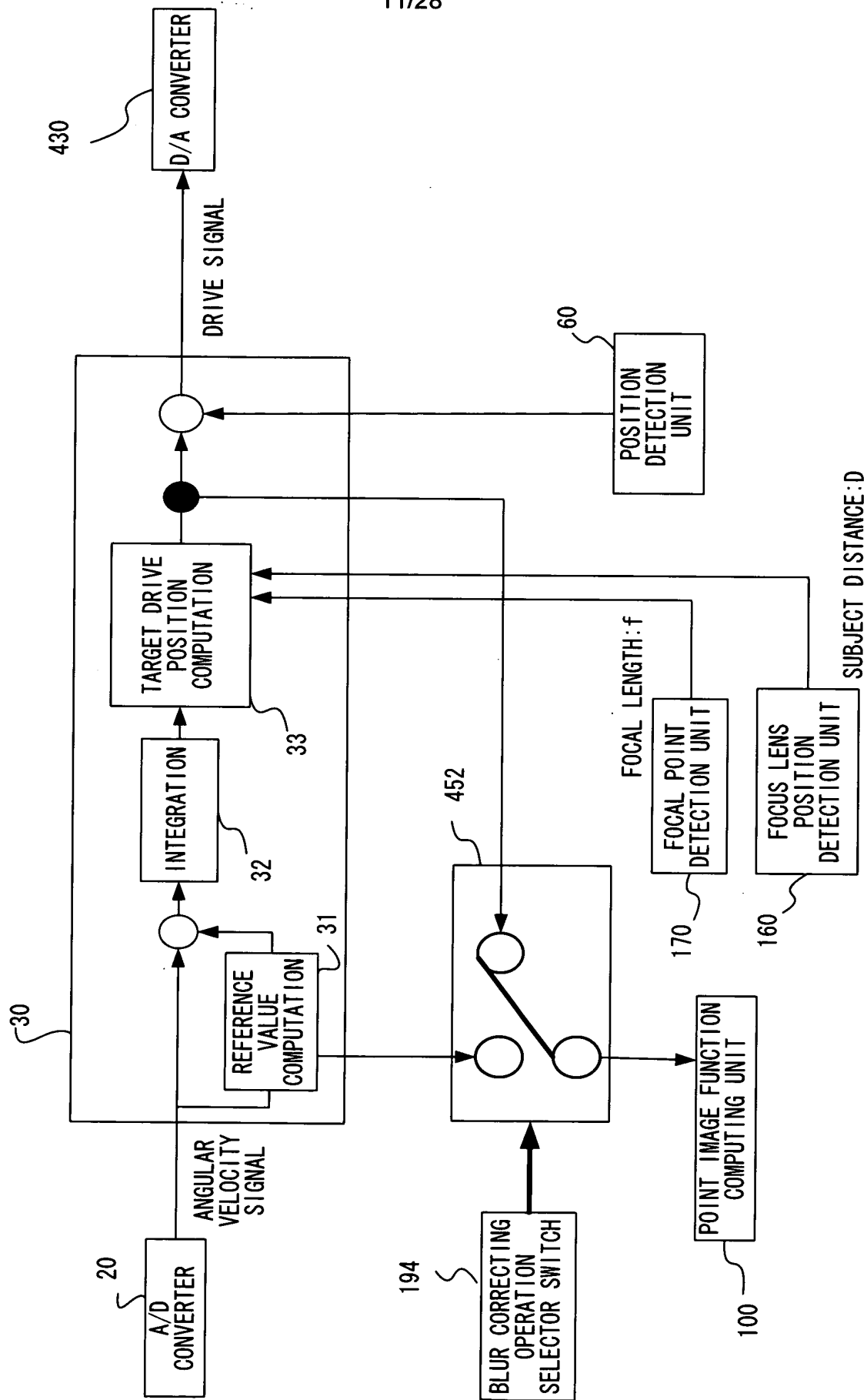


FIG. 12

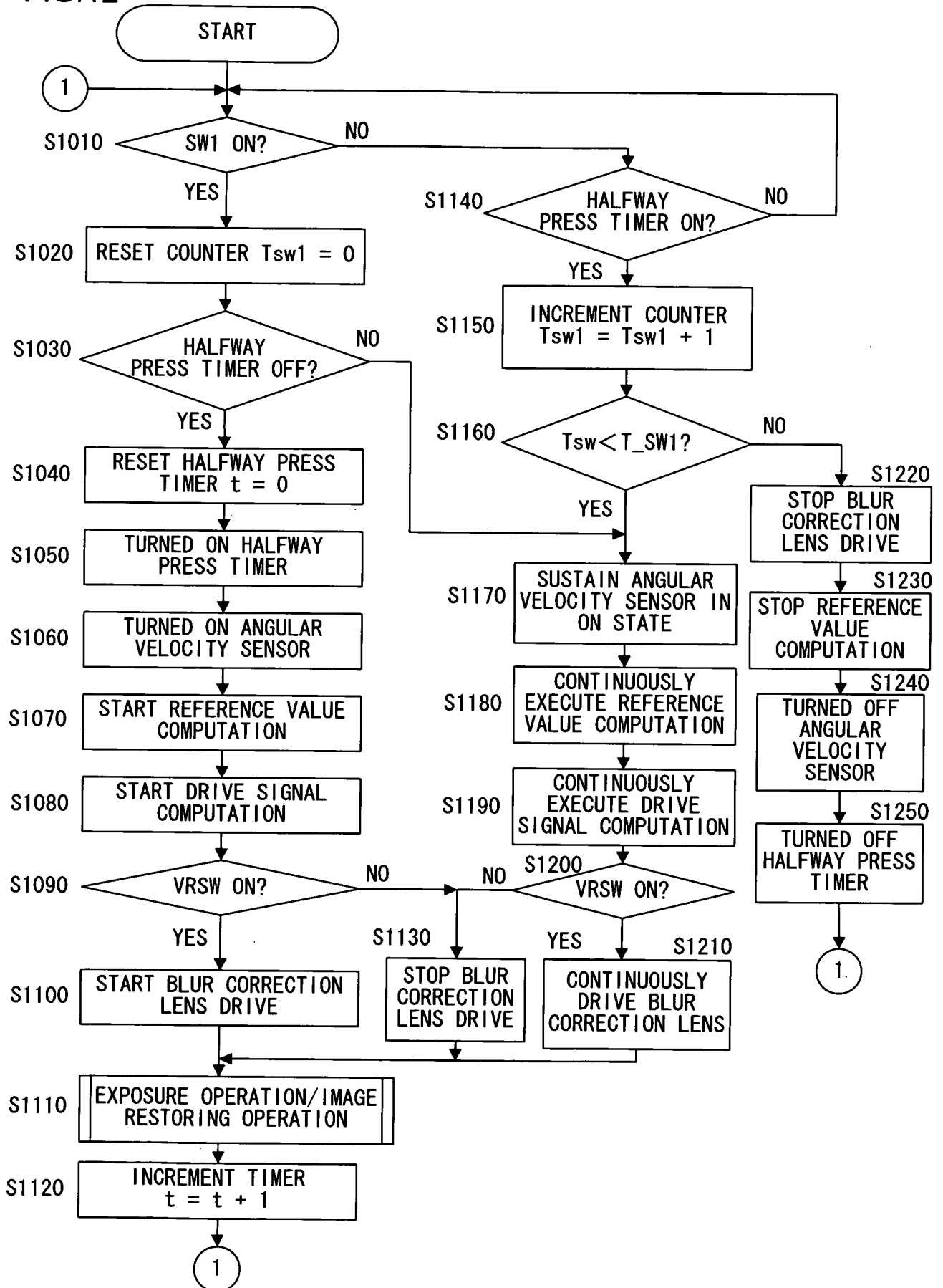
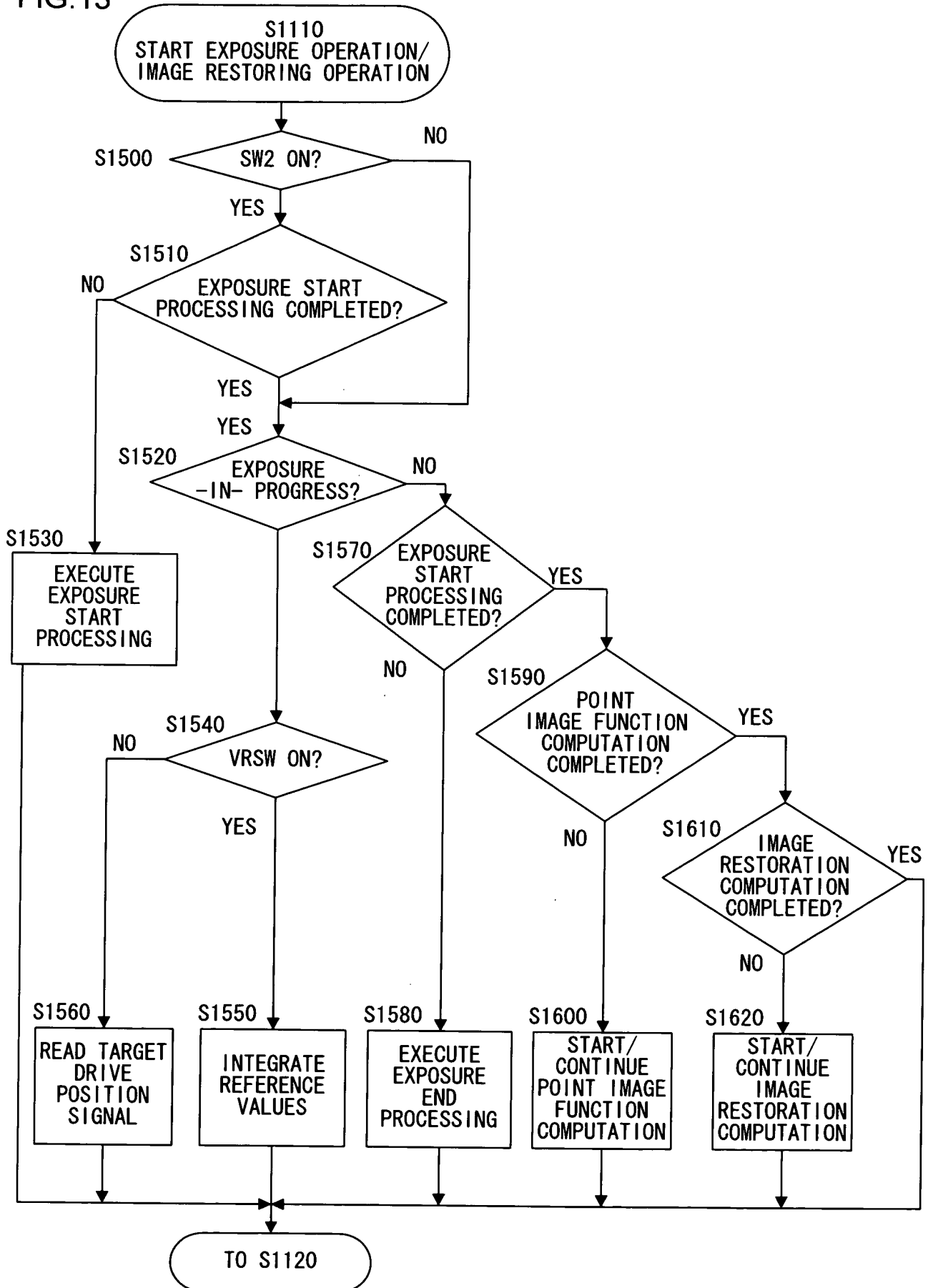


FIG.13

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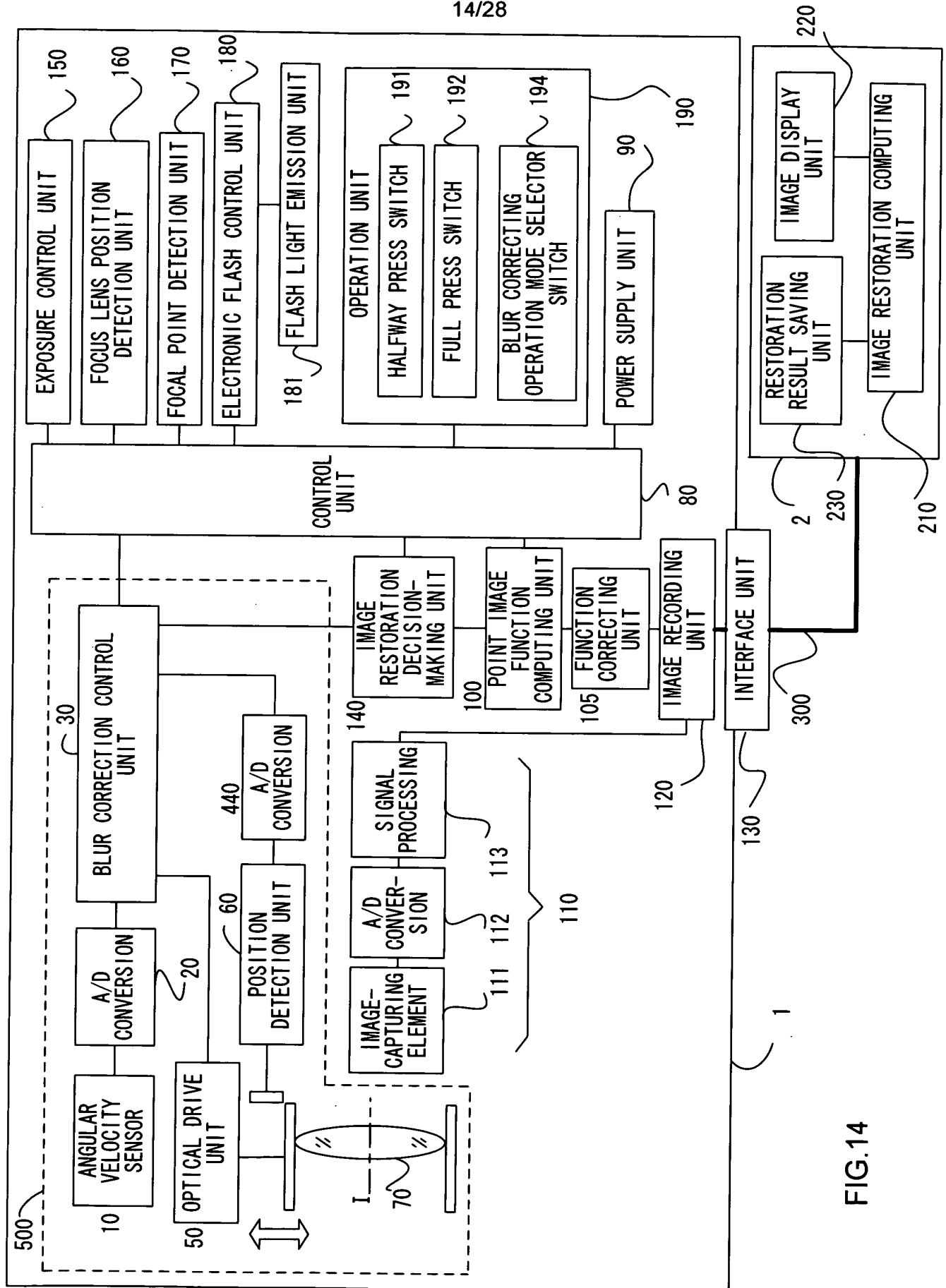


FIG. 14

FIG. 15

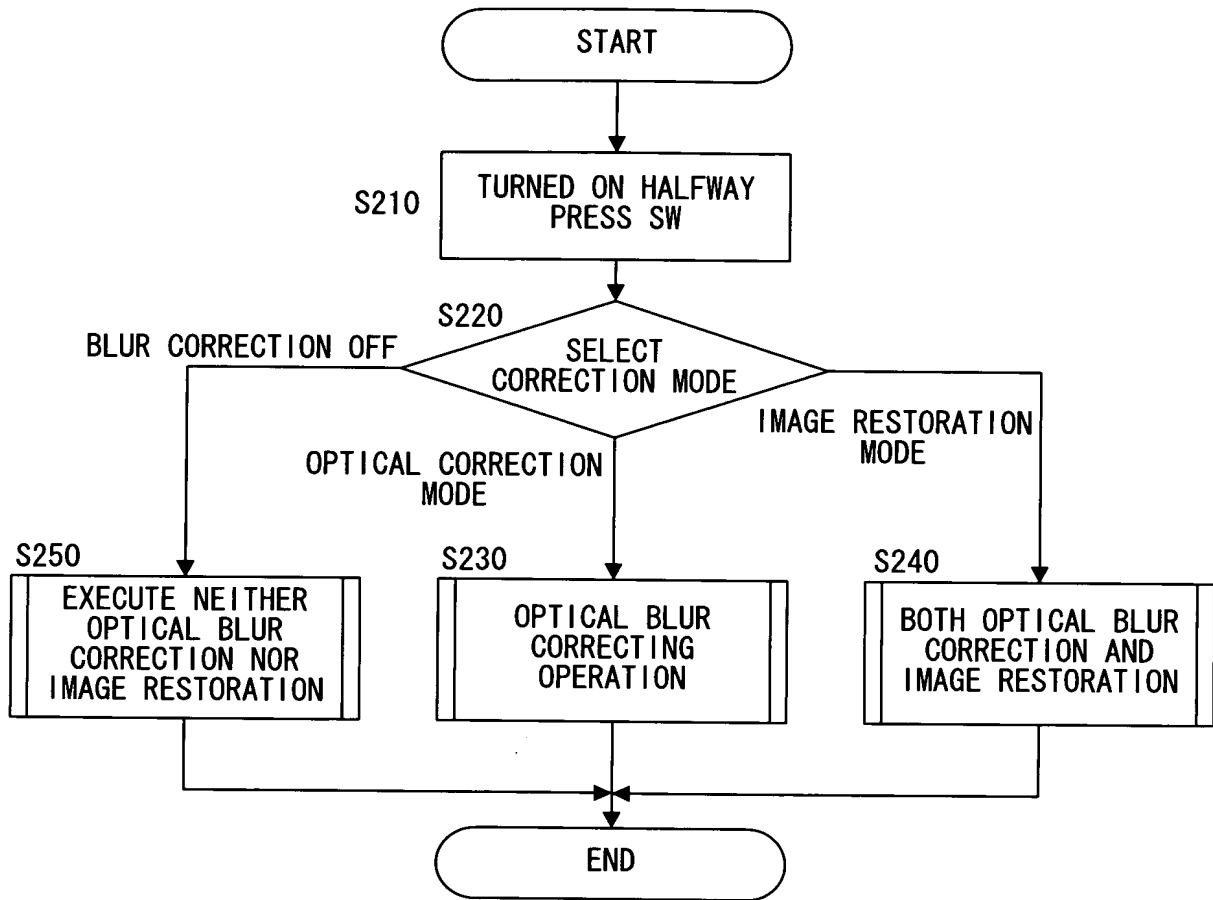


FIG.16

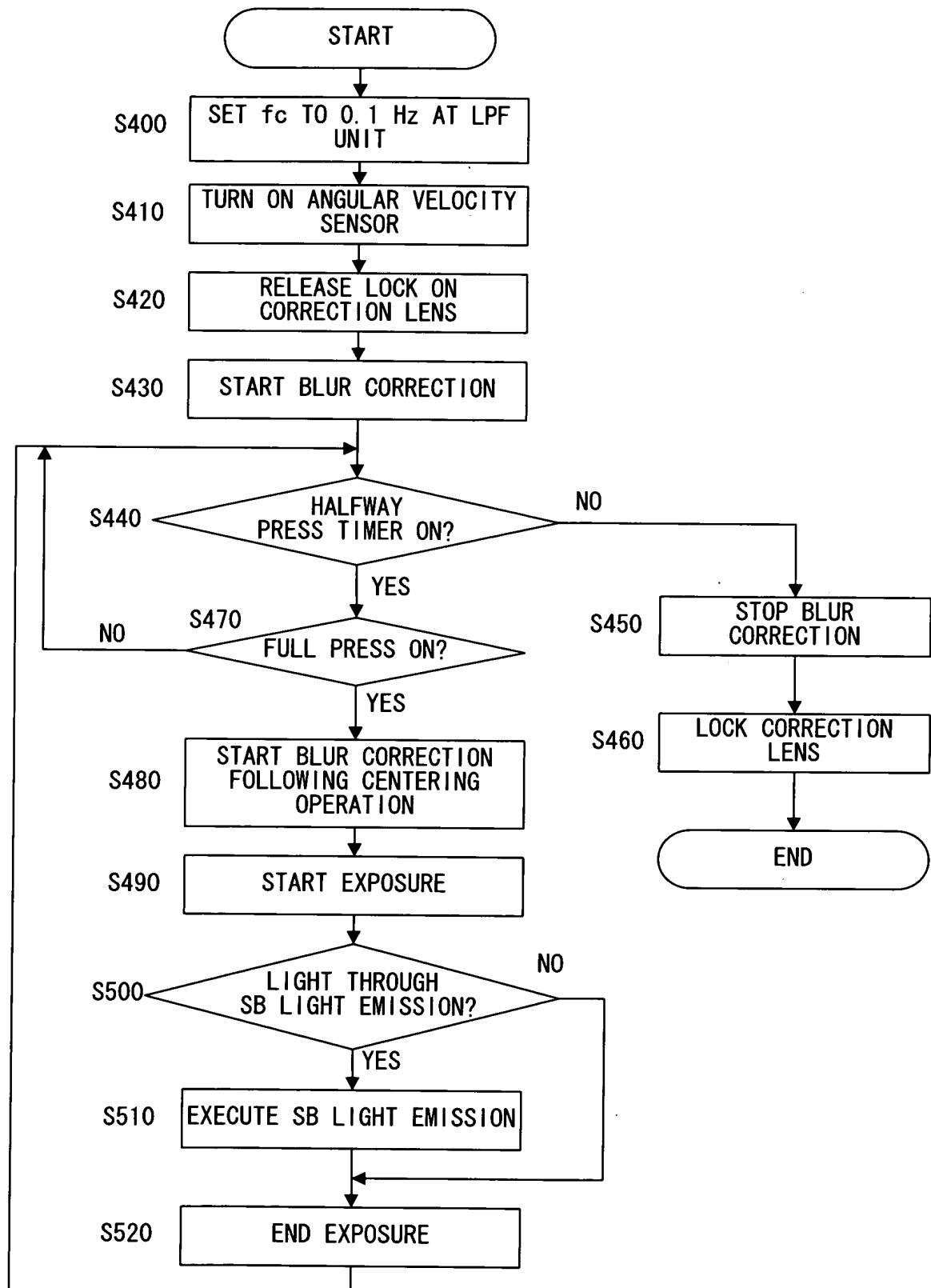




FIG. 17

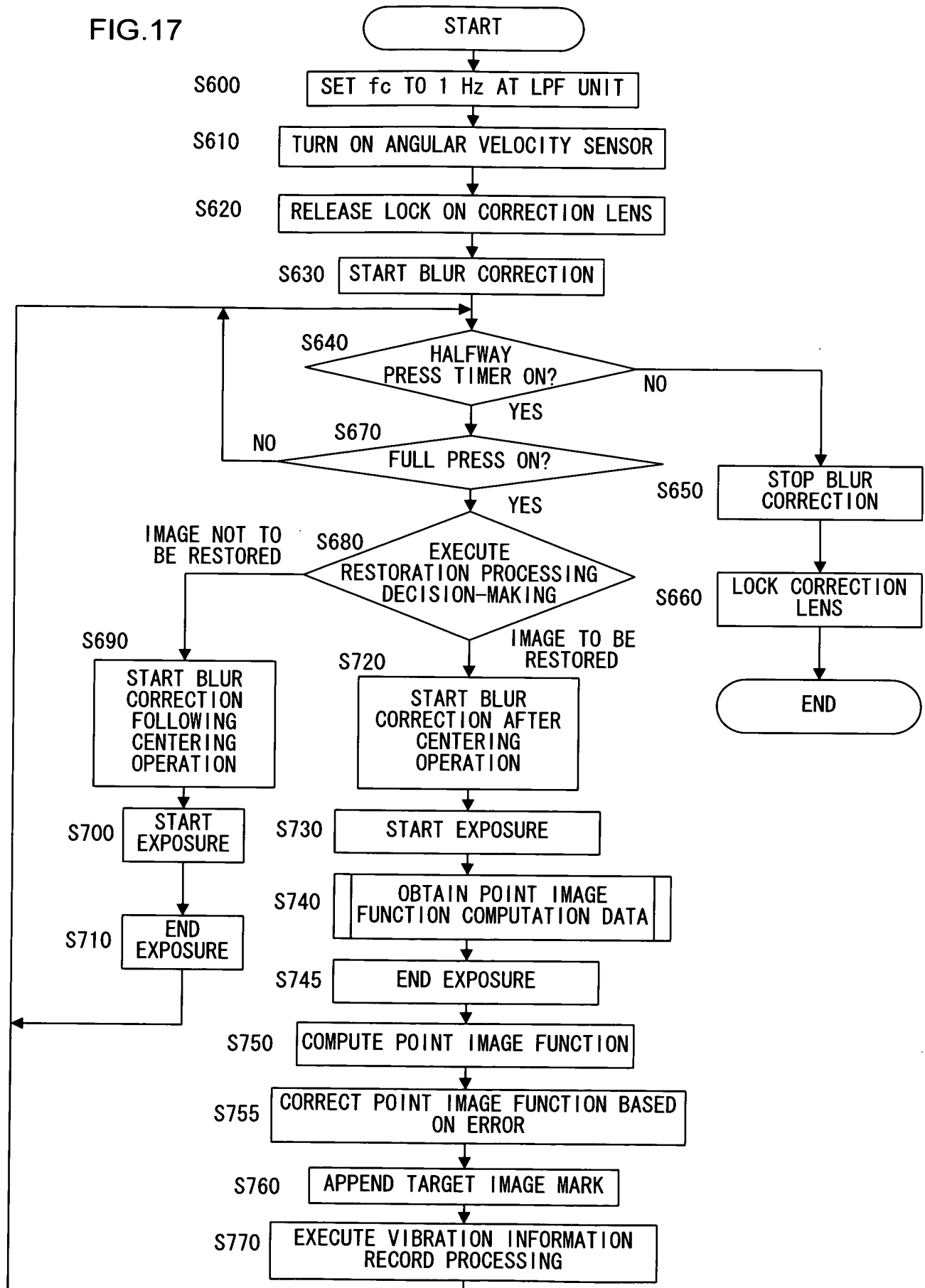


FIG.18

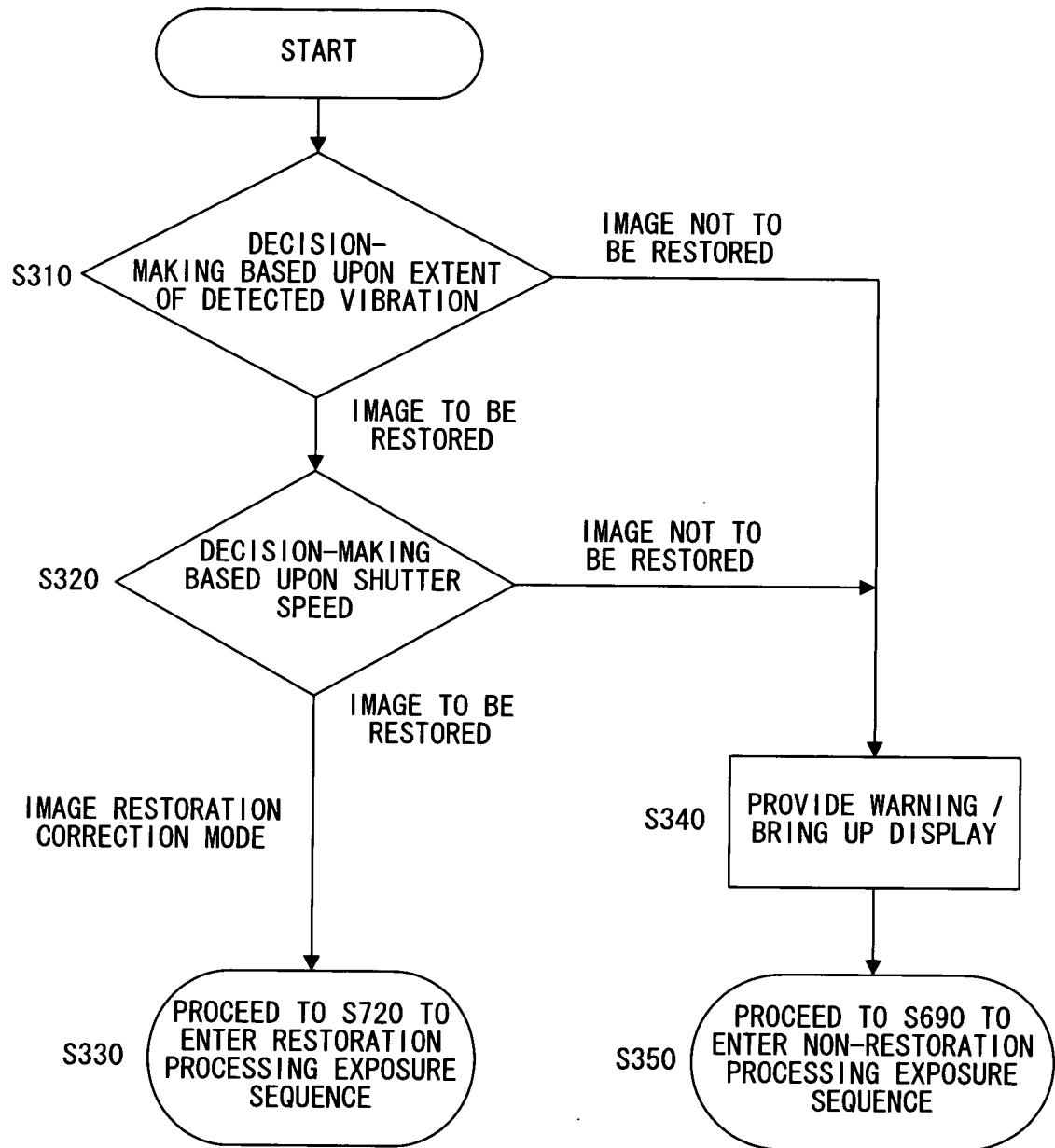


FIG. 19

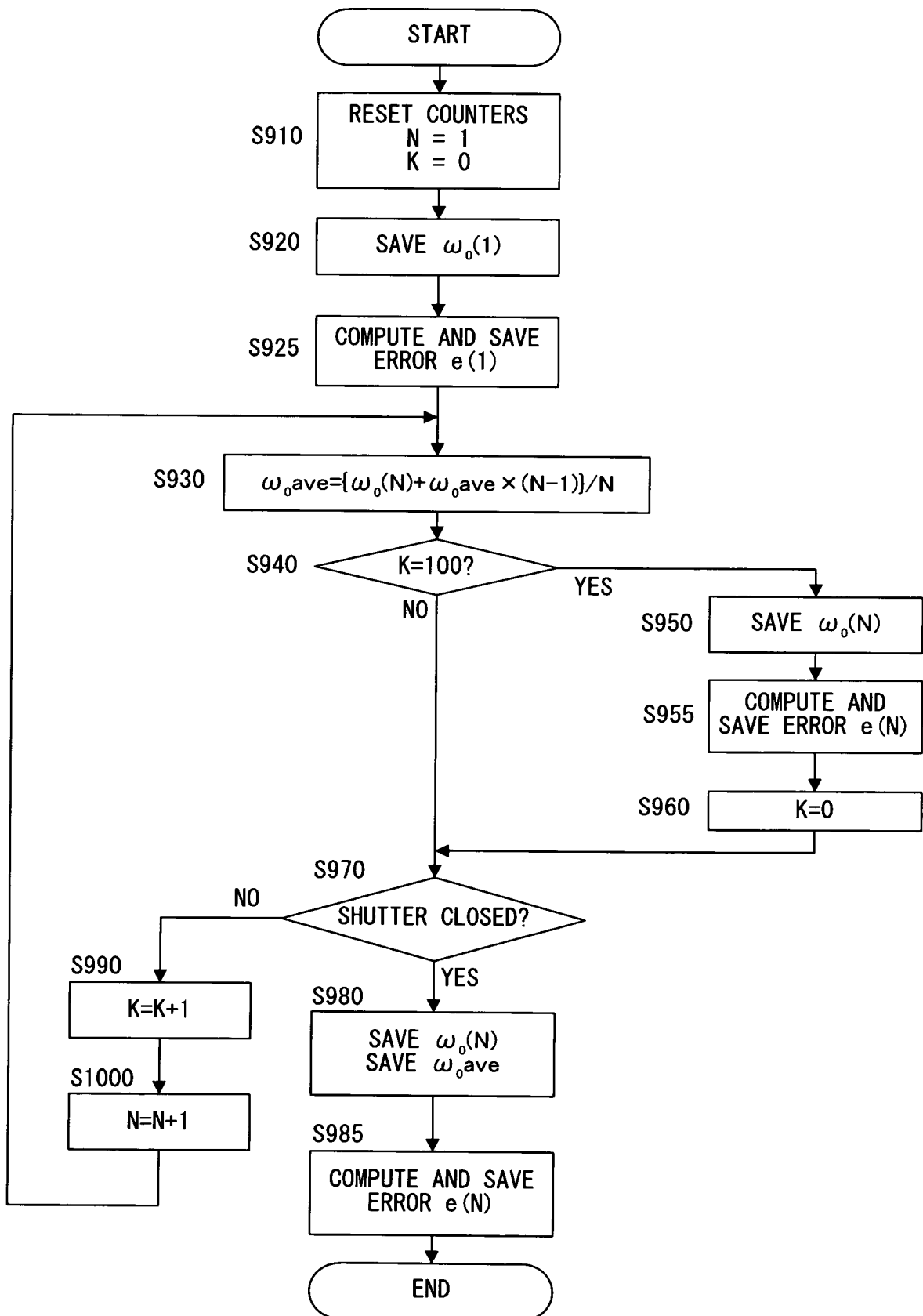


FIG.20

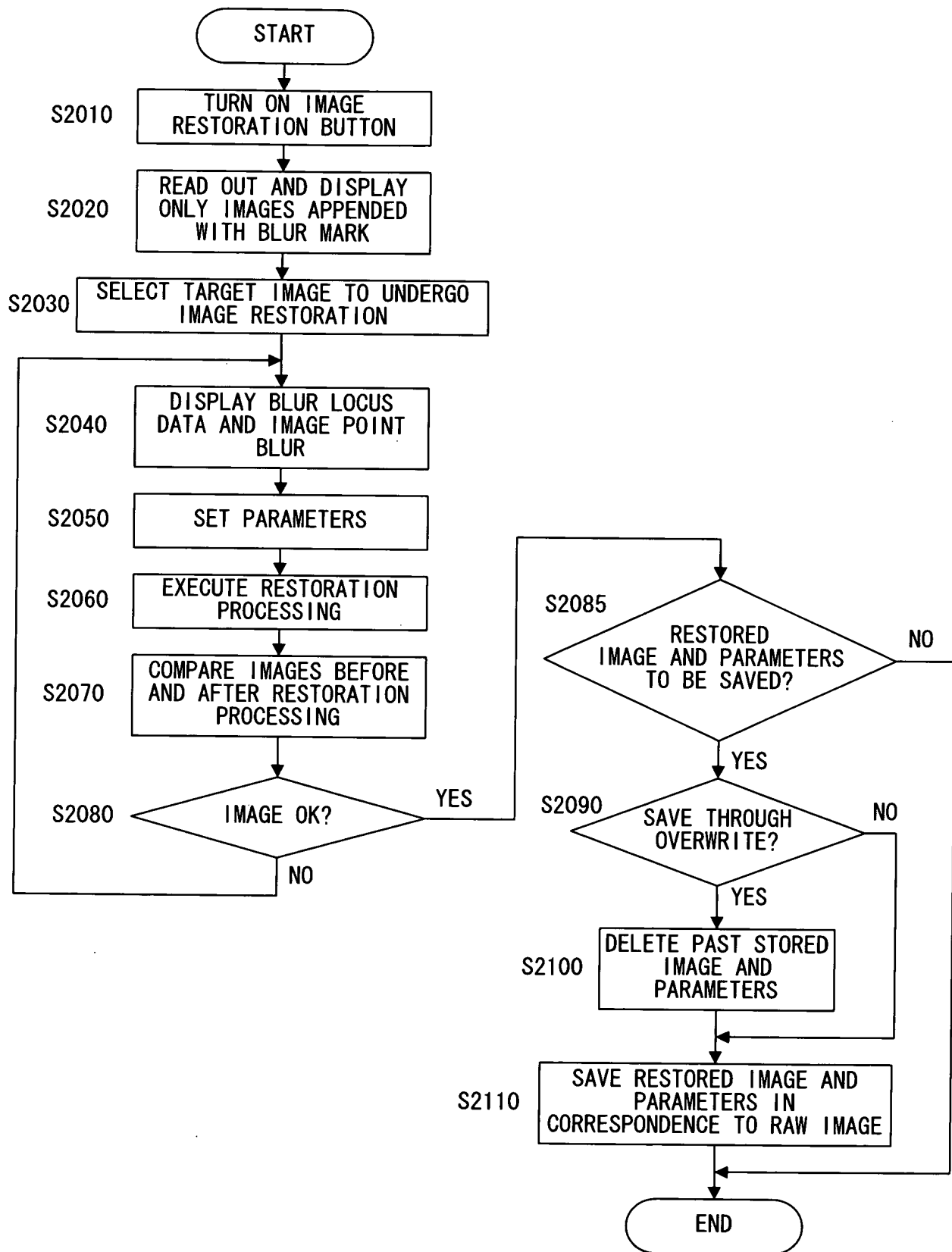
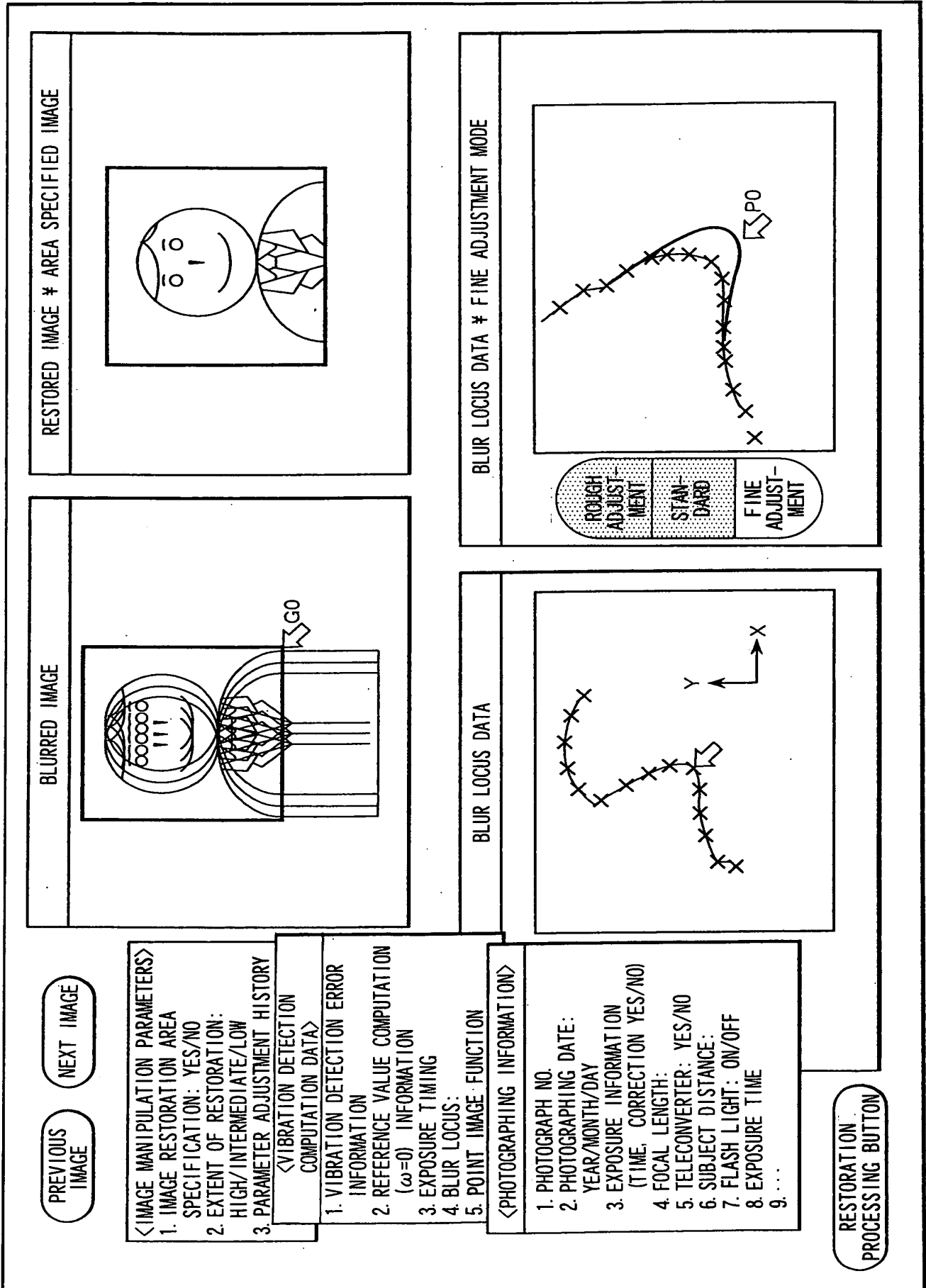


FIG. 21



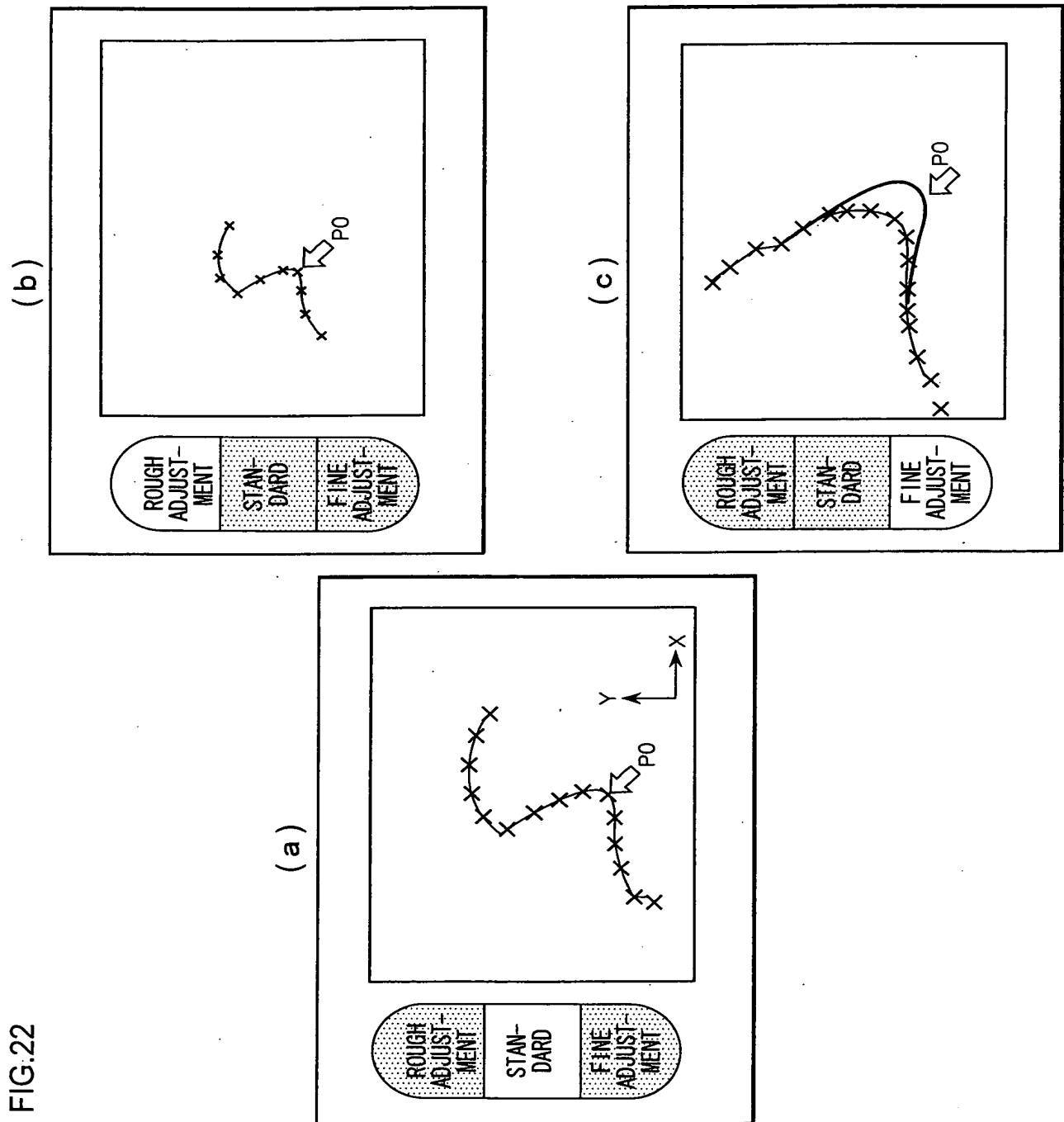


FIG.23

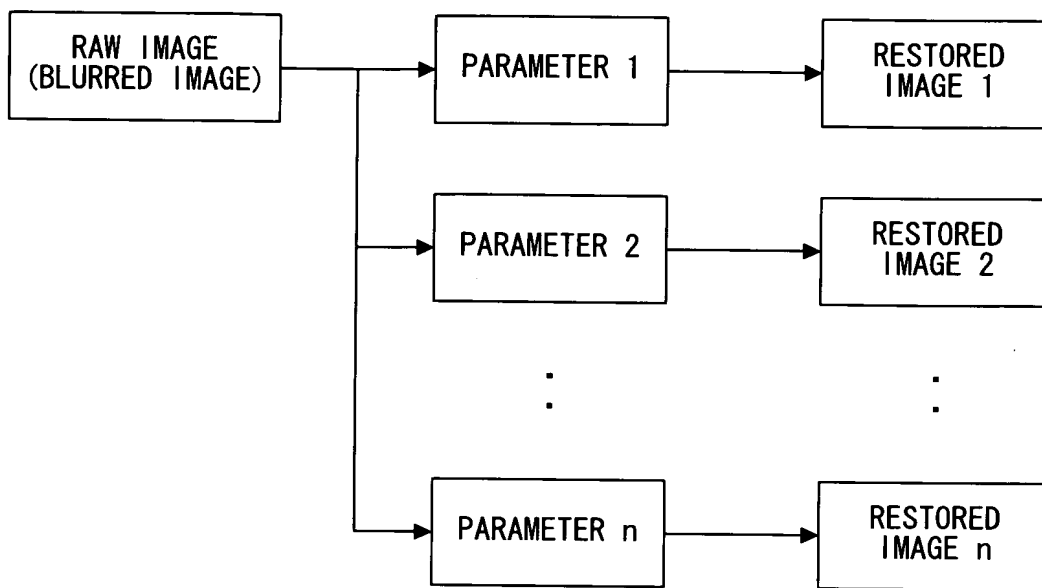


FIG.24

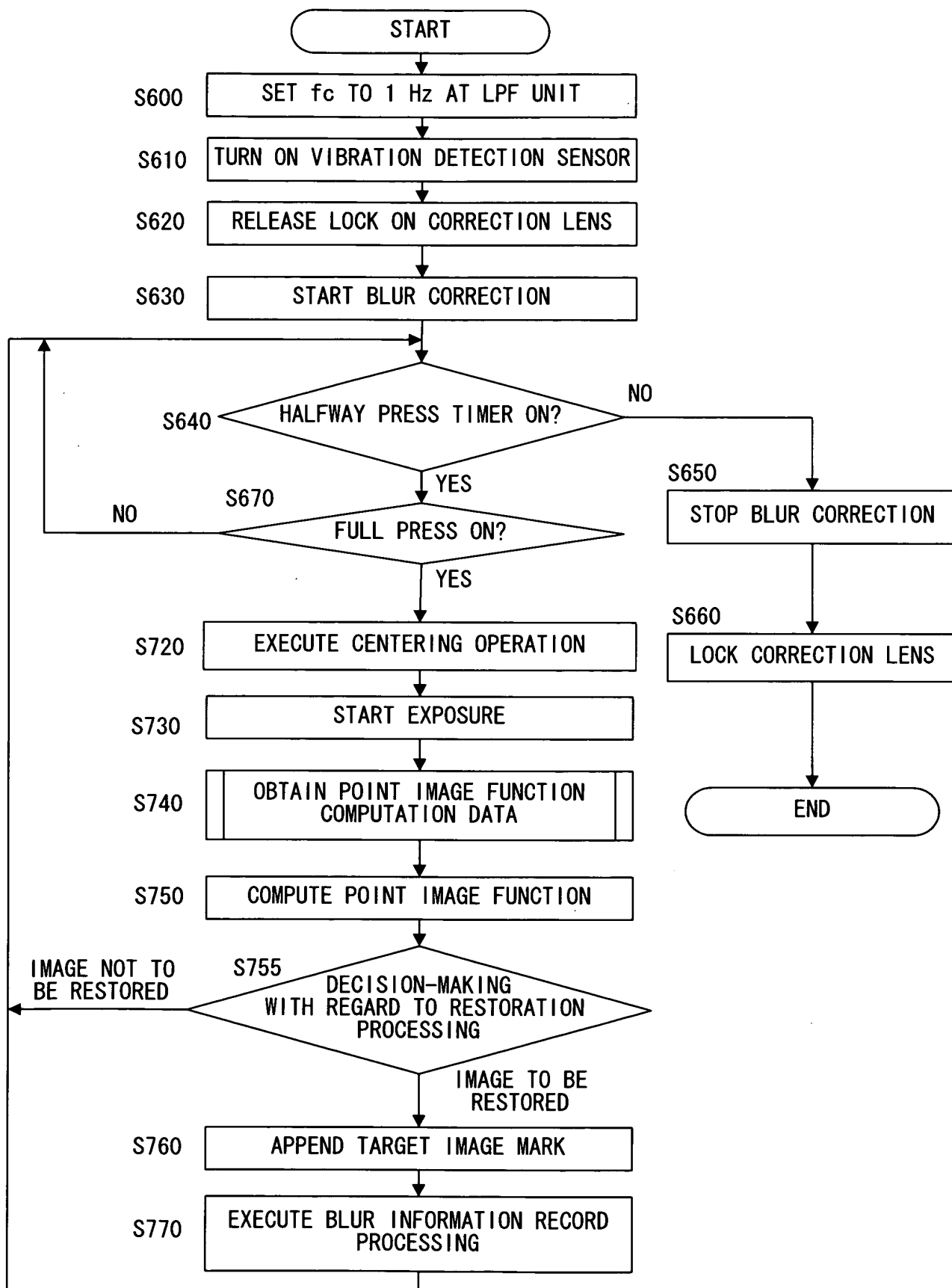




FIG.25

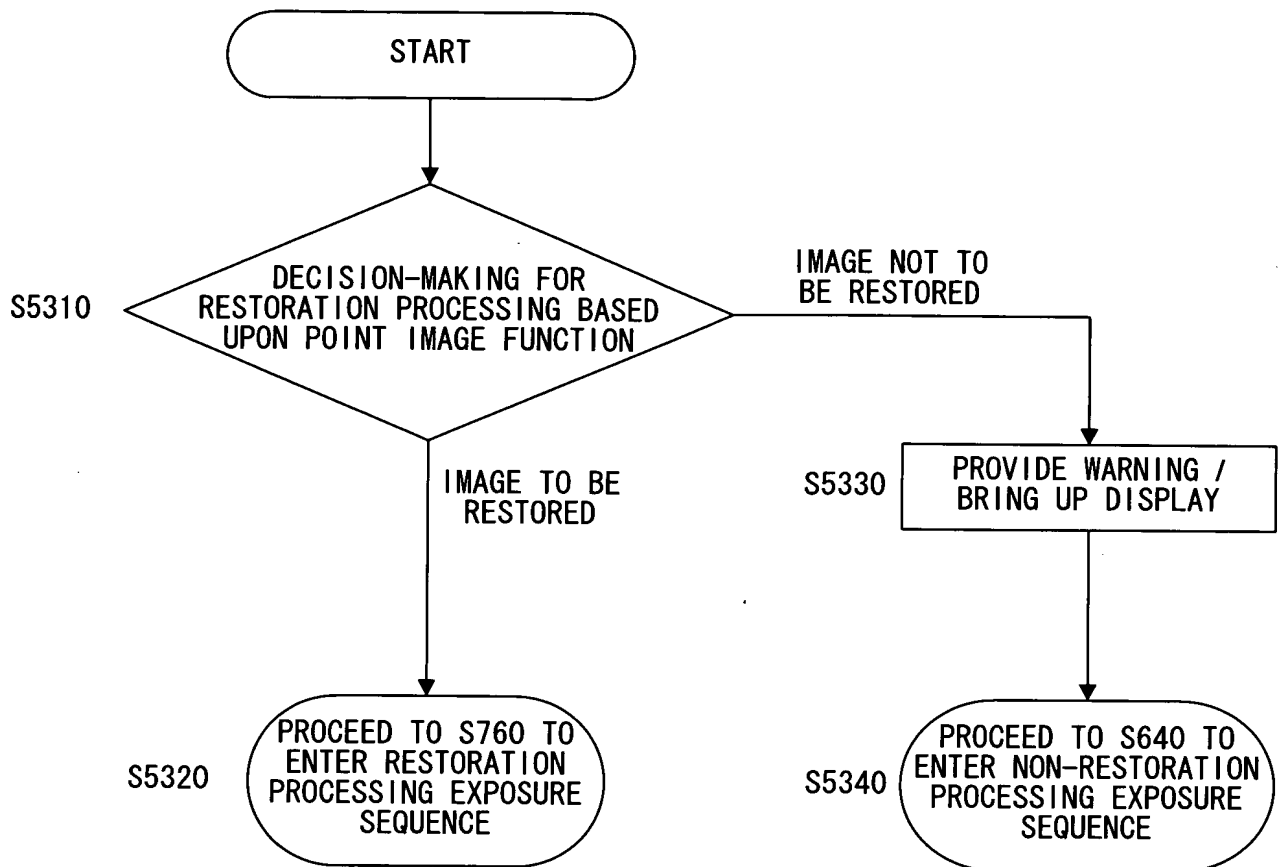


FIG. 26

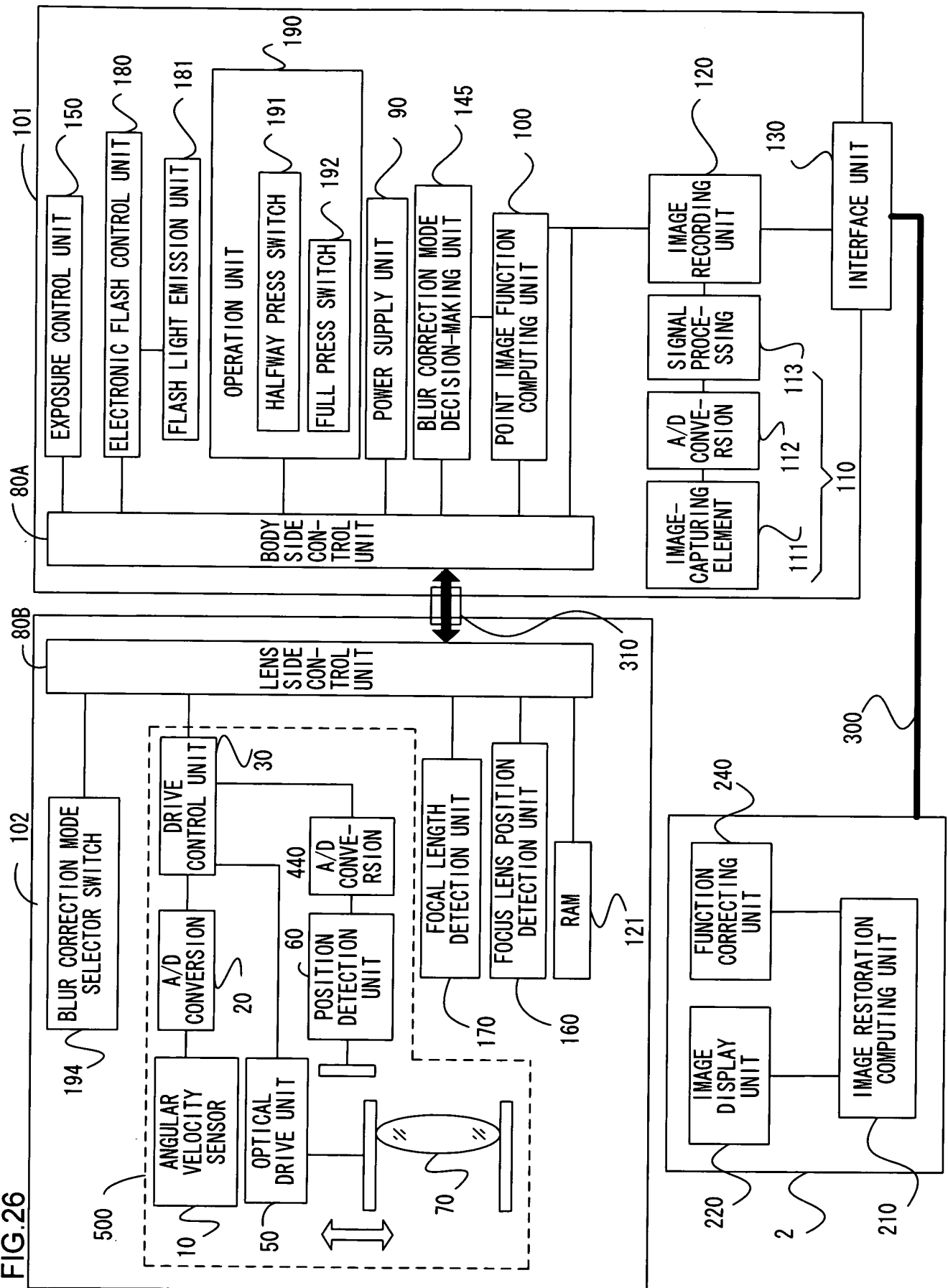


FIG. 27

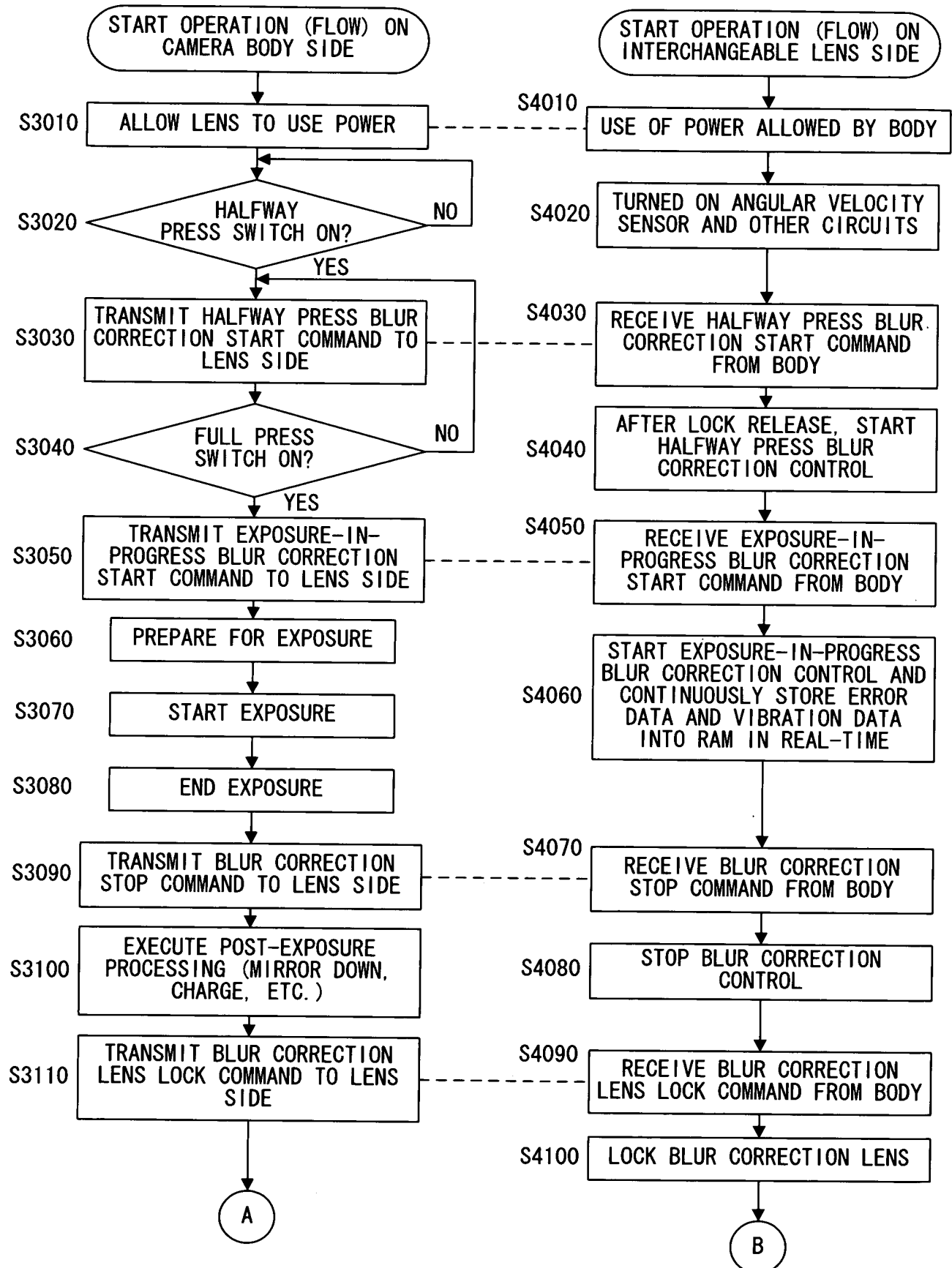


FIG.28

